Literature Study

Modeling an angiogenesis treatment after a myocardial infarction

Linda Crapts 4 april 2012



Introduction



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Outline











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(a)

Stem cell density

$$\begin{array}{l} \frac{\partial m}{\partial t} = -\beta_1 m,\\ \bullet \ m(x,0) = \begin{cases} m_0 & x \in \Omega_w,\\ 0 & x \in \Omega \backslash \Omega_w. \end{cases} \end{array}$$

$$\frac{\partial c}{\partial t} - D_1 \frac{\partial^2 c}{\partial x^2} + \lambda c = \alpha m,$$

•
$$c(x, 0) = 0$$
,
• $\frac{\partial c}{\partial x}(0, t) = \frac{\partial c}{\partial x}(1, t) = 0$



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Capillary tip density

$$\frac{\partial n}{\partial t} + \chi_1 \frac{\partial}{\partial x} \left(n \frac{\partial c}{\partial x} \right) - D_2 \frac{\partial^2 n}{\partial x^2} = \alpha_0 \rho c + \alpha_1 H(c - \hat{c}) n c - \beta_2 n \rho,$$

•
$$n(x,0) = 0$$
,

•
$$\frac{\partial n}{\partial x}(0,t) = \frac{\partial n}{\partial x}(1,t) = 0.$$

Vessel density

$$\begin{aligned} \frac{\partial \rho}{\partial t} &- \epsilon \frac{\partial^2 \rho}{\partial x^2} + \gamma (\rho - \rho_{eq}) = \mu_1 \frac{\partial n}{\partial x} - \chi_2 n \\ \bullet & \rho(x, 0) = \begin{cases} 0 & x \in \Omega_w, \\ \rho_{eq} & x \in \Omega \setminus \Omega_w, \end{cases} \\ \bullet & \frac{\partial \rho}{\partial x}(0, t) = 0, \ \rho(1, t) = \rho_{eq}. \end{aligned}$$



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$$\frac{\partial \rho}{\partial x}(0,t) = 0$$
, $\rho(1,t) = \rho_{eq}$

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(a)

Stem cell density



Amount of TG-Beta

The amount of TG-beta is determined by $\int_{\Omega} c \ d\Omega$.





Characteristics of the capillary tip density

Speed of the characteristics: $\frac{dx}{dt} = \chi_1 \frac{\partial c}{\partial x}$.





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Characteristics of the capillary tip density

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Boundary wound: $\delta = 0.2$. \Rightarrow Amount of stem cells is not enough when we have

the used parameters!

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(a)

FDM and FEM

Maximum relative difference between the finite difference method and the finite element method.

	$\Delta x = 0.001$		
	С	n	ρ
t = 0.5	0.0100	0.0286	0.0156
t = 1.0	0.0100	0.0574	0.0548
t = 1.5	0.0100	0.0567	0.0566
t = 2.0	0.0100	0.0366	0.2712



Results with FEM

The following results are with the finite element method, where we have used $\Delta x = 0.001$, $\Delta t = 0.01$ and T = 2.





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Results with FEM





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Péclet number

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$$Pe=rac{v\Delta x}{D},$$

where v is the absolute speed and D the diffusion coefficient.

If the equation is dominated by convection, we can try to improve the results by implementing SUPG.



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Pe = 0,	pure diffusion,
$Pe\leq 1$,	diffusion-dominated,
$1 < \mathit{Pe} \leq 10$,	both are important,
Pe>10,	convection-dominated,
$Pe = \infty$,	pure convection.

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Basics of SUPG

The advection equation:

$$u_t+u_x=0.$$

Multiply by a testfunction $\eta(x) = \varphi(x) + p(x)$ and take the integral over the domain:

$$\int_{\Omega} u_t \eta + u_x \eta \ d\Omega = 0,$$

$$\Rightarrow \underbrace{\int_{\Omega} u_t \varphi + u_x \varphi \ d\Omega}_{\text{FEM}} = \underbrace{-\int_{\Omega} u_t p + u_x p \ d\Omega}_{\text{Additional for SUPG}},$$

where $p(x) = \xi \frac{\Delta x}{2} \frac{d\varphi}{dx}$ and ξ equals the sign of the speed.



Advection equation with SUPG

With discontinuous initial condition, after t = 0.05.



Our model with SUPG

Péclet number equals:

$$Pe = rac{\chi_1 rac{\partial c}{\partial x}}{D_2} \Delta x.$$

FEM already worked relatively well, so we did not obtain any results yet that showed the functionality of SUPG to our model.



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$$e_j = [x_{j-1/2}, x_{j+1/2}],$$

 $j = 1 \dots N.$

- Maximum element size: $\Delta x = \max_{1 \le j \le N} \Delta j.$
- Legendre polynomials as our basisfunctions.
- Scale element interval to [-1,1] by $r = \frac{2(x-x_j)}{\Delta x}$.



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The approximation is given by:

$$u_{h}(x,t) = \sum_{l=0}^{K} u_{j}^{(l)}(t)\varphi_{j}^{(l)}(x)$$

= $\sum_{l=0}^{K} u_{j}^{(l)}(t)P_{l}\left(\frac{2(x-x_{j})}{\Delta x}\right)$
= $\sum_{l=0}^{K} u_{j}^{(l)}(t)P_{l}(r).$

So each global x, has its own local value r.

Advection equation with DG

With discontinuous initial condition, after t = 0.25. Here we have used two Legendre polynomials, so up to order K = 1.



Figuur: $\Delta x = 0.01$, $\Delta t = 0.001$.



The monotonized central-difference limiter

The limiter can be used for polynomial basis up to order K = 1. It uses the minmod function, which is given by:

$$m(a, b, c) = \begin{cases} \operatorname{sgn}(a) \cdot \min\{|a|, |b|, |c|\} & \text{if } \operatorname{sgn}(a) = \operatorname{sgn}(b) = \operatorname{sgn}(c) \\ 0 & \text{elsewhere.} \end{cases}$$

Solution using the limiter

$$u_h(x,t^k) = \bar{u}_j^k + \sigma_j^k(x-x_j).$$

Here, \overline{u}_{j}^{k} is the averaged approximation over e_{j} at t = k and σ is defined as:

$$\sigma_j^k = m\left(\frac{\bar{u}_{j+1}^k - \bar{u}_{j-1}^k}{2\Delta x}, 2\frac{\bar{u}_{j}^k - \bar{u}_{j-1}^k}{\Delta x}, 2\frac{\bar{u}_{j+1}^k - \bar{u}_{j}^k}{\Delta x}\right)$$



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Advection equation with DG and limiter



Figuur: Without limiting

Figuur: With limiting

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Further research

Our model:

- Expand the model to 2D. (Apply FEM)
- Are the parameter values realistic?
- Are the initial conditions realistic?



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Further research

Research for DG:

- Try to limit the DG approximation using higher order basisfunctions.
- Apply DG to our 1D model.
- How does DG works for a two dimensional scheme?
- Apply DG to our 2D model.



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Further research

Research question:

• How many stem cells should be injected when aiming at avoiding the formation of scar tissue?

