DELFT UNIVERSITY OF TECHNOLOGY Faculty of Information Technology and Systems

# **Matlab Manual**

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#### Contents

1	Matlab session4	ł
	1.1 Getting started with Matlab	l
1	1.2 Matlab and matrices, a general remark	ī
2	Lay-out	,
3	Common Commands	,
4	Numbers and strings	\$
5	Variables9	,
6	Complex variables	)
7	Matrices and Vectors11	L
8	Elementary mathematical functions and constants15	;
9	Conditional statements16	, )
10	Loop Statements	;
11	Output19	)
12	Input	)
13	Graphical Output21	L
14	Script files, function files23	;
15	Solving a system of equations25	;
16	Tracking down errors	)
17	Example program, time integration27	,
18	Example program, filling a penta-diagonal matrix29	)
19	Reference and index	)

### 1 Matlab session

The way to start Matlab differs from computer to computer. You may type the command 'matlab' when you are working under DOS or UNIX. Often, though, you will have to click on a specific icon in order to run the program.

#### 1.1 Getting started with Matlab

Once you have started Matlab a command window will appear, showing the command prompt:

*» % The Matlab command prompt.* 

The line after the prompt is called the command line. On this line you can give Matlab commands. After you have pressed <return>, Matlab will execute the command.

» pause(5)	%	Wait 5 seconds before showing the plot.
$\gg$ <b>plot</b> (x,y)	%	Plot vector y versus vector x.

Besides the command window Matlab has graphical windows. Output of plot commands is directed to this type of windows.

The **quit** command enables you to leave Matlab. To terminate a running Matlab command you may use **[Ctrl]+[c]** (Press both the Ctrl button and the c button simultaneously).

By using the ! symbol you can use the original operating system

» ! printer command	%	Execute the printer command belonging to the
	%	original operating system.

Only for short computations it is useful to execute Matlab straightaway from the command line. In general the next procedure is much more practical:

- 1. Make a script file (see chapter 14) by means of the available text editor. A script file consists of a sequence of Matlab commands. In general script files will contain the main program and subprograms.
- 2. If necessary make the additional function files, using the same editor. Through these files we are able to define the functions which play a role in script files.
- 3. Matlab executes the commands in the script file after you have typed the name of the script file on the command line.

From the command line background information can be obtained using

```
    help 

        » help plot % gives information on the Matlab command plot.
    demo
```

```
» demo % presents multiple examples of the usage of Matlab.
```

#### 1.2 Matlab and matrices, a general remark

Suppose that we define vectors x, y and a matrix z by

 $\begin{array}{ll} x(i) = i & , i = 1, \, ..., \, 10, \\ y(i) = i^2 & , i = 1, \, ..., \, 10, \\ z(i, j) = sin(x(i) + y(j)) & , i, j = 1, \, ..., \, 10. \end{array}$ 

In most programming languages a computer implementation will be done using nested loops:

In Matlab this can be done quite differently, because matrices are basic objects:

» 
$$x = 1:10; y = 1:10; y = y^2;$$
  
»  $z = sin(x+y);$ 

Both programming styles are possible in Matlab. In this manual we prefer the latter and all examples will be given in this style.

#### 2 Lay-out

When you use Matlab's default configuration, the program distinguishes upper case and lower case characters.

If the default configuration is used, Matlab will also print the result after every command. Typing ; after the command will suppress this.

» x = 2 % Matlab prints the result x = 2» x = 2; % Matlab does not print the result

The symbol % is used to give comments.

$\gg x = 2$	%	gives the value 2 to x and prints the result
	%	printing the result can be suppressed with;

The symbol ... denotes that the command continues on the next line

$$x = 1 + 2 + 3 + 4 + 5 + 6 + 7 + 8 + 9 + 10 \dots \\ + 11 + 12 + 13 + 14 + 15 + 16 + 17 + 18 + 19 + 20; \\ \%$$
 this command does not fit on one line

# Common Commands

quit	:	leave Matlab
help command name	:	gives information about a command
↑↓	:	retrieves preceding and following commands
pause	:	pauses execution, Matlab will proceed after <return></return>
whos	:	gives a list of Matlab variables stored in the memory
clear	:	clears the memory
clc	:	clears the command window
clf	:	clears the graphical window
shg	:	brings the graphical window to the foreground
cputime	:	determines the elapsed cpu time
demo	:	activates Matlab demonstrations

#### **4 Numbers and strings**

Numbers can be entered in Matlab in the usual way.

Matlab automatically assigns a type for every number you enter. Depending on the type, Matlab chooses an internal representation for these numbers and the corresponding computations. The external representation of a number (e.g. on the screen) can be altered with the format command.

format long e	:	16 digits, (exponential) floating point 3.141592653589793e-02	
format short e	:	5 digits, (exponential) floating point	3.1416e-02
format short	:	5 digits, fixed point	0.0314
format long	:	15 digits, fixed point	0.03141592653590
format	:	returns to the default configuration	

The default configuration is 'format short'. It might be possible that the local system manager has changed this into short e.

- <u>Remark:</u> The **format** command influences only the external representation of real numbers. This command has no influence on the internal representation used by Matlab to process the program and its computations.
- <u>Remark:</u> The **format** command is not able to alter the external representation of integer numbers. This can result for example in jumps in tables.

To manipulate text, Matlab uses strings.

> disp ('give the spring constant a')
give the spring constant a

#### **5 Variables**

A variable's name has to start with a letter, but may not contain more than 31 letters, digits, or underscores. Matlab automatically reserves space in the computer's memory to store the variable. Variables do not need to be declared before use; Matlab derives the type of the variables by looking at the stored data. So it is possible that the type of a variable changes while a session is in progress.

The basic element of Matlab is the matrix. Depending on the size of the matrix we distinguish scalars  $(1 \times 1 - \text{matrix})$ , vectors  $(1 \times m -, \text{ or } m \times 1 - \text{matrix})$ , etc. Depending on the context Matlab also assigns the type of the variables in the matrix, e.g. real or complex.

The operators +, -, \*, /,^ can be used for all Matlab variables  $(x \land y = x \text{ to the power of } y)$ . In the scalar case these operations will reduce to the usual computations. At every operation step Matlab checks if the dimensions of the matrices involved are correct.

» a = 1; c = 1 + i; v(1) = 1; v(2) = 2; word = 'text';

The command whos (see section 3) gives:

Name	Size	Class
а	1 x 1	double array
c	1 x 1	double array (complex)
V	1 x 2	double array
word	1 x 4	char array

Multiplying a vector v with itself is not possible. If we try this anyhow we get:

$$\gg w = v * v;$$

??? Error using  $\rightarrow *$ Inner matrix dimensions must agree.

### **6** Complex variables

A complex number can be defined using the imaginary number i.

$$> c = 1 + i$$
  
 $c =$   
 $1.0000 + 1.0000 i$ 

The operators +, -, \*, /, ^ also work for complex numbers. With the symbol ' we conjugate a complex variable:

The (square of the) modulus of c can be computed in the following way:

An alternative way is:

Imaginary and real parts of a variable can be obtained with the functions real and imag:

$$a = real (c)$$
  
 $a = 1.0000$   
 $b = imag (c)$   
 $b = 1.0000$ 

#### 7 Matrices and Vectors

Matlab stores its variables in matrices of size n x m. If m = 1, we are dealing with a column vector, and if n = 1, with a row vector. When n = m = 1 the matrix represents a scalar. The size of a matrix does not have to be given; Matlab determines the size from the data given by the user. Matlab does not recognize a more general array structure, for example v (-10:100); the lower bound in Matlab is always equal to 1.

We can define matrices in different ways, e.g. by giving values to every element separately. We separate row entries with a space or comma and columns with a semicolon.

 $A = \begin{bmatrix} 1 \ 2 \ 3; 4, 5, 6; 7 \ 8 \ 9 \end{bmatrix}$  generating matrix A  $A = \begin{bmatrix} 1 \ 2 \ 3 \\ 4 \ 5 \ 6 \\ 7 \ 8 \ 9 \end{bmatrix}$   $A = \begin{bmatrix} 1 \ 2 \ \dots \\ 3 \ 4; \\ 5 \ 6 \ 7 \ 8 \end{bmatrix}$  generating matrix A; ... means continuation  $A = \begin{bmatrix} 1 \ 2 \ 3 \ 4 \\ 5 \ 6 \ 7 \ 8 \end{bmatrix}$ 

Vectors can also be made using the colon symbol : . Here the first value stands for the initial value, the second for the step size and the third for the final value in the vector.

$\gg x = 0$ :	0.2:1	%	generating row vector x			
x = 0	0.2000	0.4000	0.6000	0.8000	1.0000	

Sometimes it is good to use one of the following Matlab functions:

zeros(n,m): gives an n x m matrix with zeros							
ones(n,m) eye(n)	:	gives an n x m matrix with ones gives the n x n identity matrix					
$\gg A = ones$	(3,3) -	+ 2* <b>eye</b> (3)	%	generating	matrix A		
A =							
3 1 1 1 3 1							
113							

Matrices can also be built from variables

$$> v = ones(3,1); A = [-v \ 2^*v \ -v] \qquad \% \qquad generating \ matrix \ A = \\ -1 \ 2 \ -1 \\ -1 \ 2 \ -1 \\ -1 \ 2 \ -1 \\ -1 \ 2 \ -1 \\ \end{array}$$

Matrices can also be constructed from smaller matrices

Large diagonal band matrices can be made by using the function

diag(v,k	x) :		rns a s ne vec	-	matri	x with on the k-th upper diagonal the entries
$\gg v = 1$	: 2 : 9				%	generating vector v
$v = 1 \ 3 \ 5 \ 7 \ 9$						
$\gg A = d$	iag(v,-1	') + <b>ey</b>	<b>e</b> (6) +	2*dia	<b>ig</b> (v,1)	
A =						
1	2 1 3 0 0 0	0	0	0	0	
1	1	6	0	0	0	
0	3	1	10	0	0	
0	0	5	1	14	0	
0	0	0	7	1	18	
0	0	0	0	9	1	
-1						

Matrix elements can be used separately or in groups:

A(i , j)	=	A <sub>ij</sub>
A(:,j)	=	j <sup>th</sup> column of A
A(i , :)	=	i <sup>th</sup> row of A
A(i, j1:j2)	=	vector existing of the entries, from column j1 to j2, of row i
A(i1:i2 , j1:j2)	=	matrix existing of the entries, from column j1 to j2, of the
		rows i1 to i2.

 $\gg$  plot (x(75:125), y(325:375));

In case one of the dimensions equals one we are dealing with a vector. We can refer to this vector with just one index. This index is either a row index or a column index, depending on the type of the vector.

The operators  $+, -, *, /, ^{\circ}$  can also be used for matrices. For every operation Matlab checks if the dimensions of the matrices involved are correct.

» 
$$v(1) = 1; v(2) = 2; v(3) = 3; A = eye(3);$$
  
»  $w = A * v;$   
??? Error using  $\rightarrow *$   
Inner matrix dimensions must agree.

Matlab assumes that the index of every new vector is a column index, i.e. unless explicitly specified otherwise (see example below), the new vector is a row vector. Hence in the example above v is a row vector, which results in an error message.

> v = zeros(3, 1); % v is now a column vector» v(1) = 1; v(2) = 2; v(3) = 3; A = eye(3);  $\gg w = A * v$ :

If we use . (dot) as a prefix, we can do some of the operations element by element.

$\gg v = v1.*v2;$	%	multiply v1 and v2 element by element.
	%	$v(1) = v1(1) * v2(1), \ldots, v(n) = v1(n) * v2(n).$

Furthermore the next functions and operations are often quite useful

, size(A) length(v) norm(v) norm(v,inf)	· · · ·	i.e. $norm(v) = sqrt(sum(v.^2))$ .			
>> $B = A';$ >> $v(1) = 1; v(2)$ >> $v = v';$ >> $w = A * v;$ >> $inprod = v' *$	) = 2;	<ul> <li>% transpose A</li> <li>v(3) = 3; A = eye(3);</li> <li>% change v into a column vector</li> <li>% inner product if v is a column vector.</li> </ul>			
inprod = 14					
$\gg normv2 = normv2$	m(v)				

$$normv2 = 3.7417$$

$$\gg normvinf = norm(v, inf)$$

$$normvinf = 3$$

### 8 Elementary mathematical functions and constants

Some of the predefined constants in Matlab are:

pi	:	the constant pi
i	:	the imaginary unit

The following mathematical functions operate on each element of the variable separately:

abs sqrt exp log log10	:	absolute value square root exponential function natural logarithm logarithm with base 10
sin cos tan atan	:	sine cosine tangent arctangent
round rem	:	round off to the nearest integer remainder after division

For vectors are available:

max	:	maximal element
min	:	minimal element
sum	:	sum of the elements
norm	:	the norm    v
» max(a	ıbs(v))	% computing the largest element of v, irrespective of its sign

For matrices we mention

eig	:	determines the eigenvalues of a matrix
lu	:	determines the LU-factorization of a matrix (using permutations if
		necessary).
chol	:	determines the Cholesky factorization of a symmetric matrix

#### 9 Conditional statements

In Matlab six relational operators can be used to compare variables or evaluate expressions

- smaller than
  smaller than, or equal to
  greater than
- >= : greater than, or equal to
- == : equal to
- ~= : not equal to

Furthermore there are three logical operators:

&	:	and
	:	or
~	:	not

An example of a logical expression is

```
x > 1 \& (y \le 5 | z = 1)
```

Conditional statements are, for example:

Syntax conditional statement:

if condition commands end

```
Syntax single conditional statement:

if condition

commands [1]

else

commands [2]
```

end

```
Syntax multiple conditional statement:

if condition

commands [1]

elseif condition

commands [2]

else

commands [3]
```

#### end

The condition has to be a logical expression.

An example:

### **10 Loop Statements**

#### FOR - loop

Syntax:

```
for variable = start value : increment : end value commands
```

end

The increment can be positive as well as negative. If not defined, Matlab will use increment 1 as a default.

» for j = 0 : 10 v(j + 1) = j \* .1; % the row vector v needs to start at index one! end

#### WHILE - loop

Syntax: while condition commands end

The condition needs to be a logical expression.

Note that this is not a proper method when we want to execute the loop statement exactly ten times. In Matlab 10 times 0.1 is just a bit less then 1, because Matlab makes round-off errors. This means that the loop will be executed 11 times in stead of 10 times, and therefore the final value of x will be too big:

 $\gg x$ x =1.1000

### **11 Output**

Output can be directed to the screen with the command disp.

disp (x)	:	print the value of the variable x
disp ('text')	:	print the string 'text'
<b>disp</b> (A(:,5))	:	print the 5-th column of matrix A

With the command **format** we can define how a number is displayed (see section 4).

<u>Remark:</u> Advanced control mechanisms for printing are available with the command **fprintf.** (see the example program or use **help fprintf**)

We can write data to a file.

cuil wille auto to a life.		
<b>save</b> data varlist		: the variables in varlist are written to the file data.mat in binary format. This file can be used in a subsequent session.
save output varlist - as	scii	: the variables in varlist are written legible (8 digits,
<b>diary</b> output		<ul><li>floating point) to the file output. If necessary this file can be printed.</li><li>makes a diary of everything which happens during</li></ul>
ulary output		the session and writes this to the file output. If
diary off		<ul><li>necessary this file can be printed.</li><li>stops monitoring the session.</li></ul>
» diary output	%	open the file output as output file
» disp ('x y')	%	display the header of the table
≫ <b>for</b> j = 1 : 10		
disp ([x(j) , y(j)]) <b>end</b>	%	display the values
» diary off		

- <u>Remark:</u> The **diary** command easily gives an unnecessarily amount of output. Therefore: Use the **diary** command in a selective way and only at places where output is needed.
- <u>Remark:</u> Files can be printed using the printer command of the original operating system, see section 1.
- <u>Remark:</u> Depending on the operating system other printer commands might be available. Be careful in using these commands, because they can cause an unnecessarily long waiting time for other people who want to use the printer. Using the printer command under MS-windows (in the file menu) you can print the whole Matlab session.

### 12 Input

Variables can be entered in Matlab in different ways. The first method is using the command line. We already explained how to do this. Another way to enter it is:

» x = input ('x-coordinate =');

This command writes the text from the string to the screen, waits for input (until a <return> is given) and assigns the value given by the user to the variable x. The following command:

» load data

fetches the binary file data.mat. The file data.mat needs to be produced beforehand in Matlab and besides a list of variables it also contains the values of these variables.

The command

#### » load data.txt

fetches an ASCII file with the name *data.txt*. The content is stored in a double precision array with the name data. The file *data.txt* is only allowed to contain numbers, separated by blanks. Each line of the file corresponds with a row in the array data. Each number on a line corresponds with a column in the array data. The number of columns must be equal on each line.

### **13 Graphical Output**

General commands in favour of the graphical screen are:

clf	:	clear graphical window
shg	:	show graphical screen (bring graphical screen to the foreground)
hold on	:	keep the contents of the graphical screen during new plot commands
hold off	:	erase the contents of the graphical screen before executing new plot commands
print print filename	:	direct the graph to the printer store the graph in the file 'filename'

Commands in favour of the layout of the graph are:

<b>axis</b> ( [xmin xmax ymin ymax] )	:	sets the axes according to the given values
grid	:	adds a grid to the graph
title('text ')	:	writes text above the plot
xlabel('text ')	:	writes text underneath de x-axis
ylabel('text ')	:	writes text next to the y-axis
<b>text</b> (x, y, 'text ')	:	writes text at the point $(x,y)$ of the graphical
		screen
t = num2str(var)	:	makes text of the value of var, which can
		for example be written to the screen with
		<b>text</b> (x,y,t).

The most important plot command in favour of data representation is plot:

plot (y)	:	plots the vector y versus the indices 1,, n.
plot (x,y)	:	plots the vector y versus the vector x; x and
		y must be of the same length.
<pre>plot (x,y, 'symbol')</pre>	:	plots the vector y versus the vector $x$ by
		using a symbol or color, e.g. ':' (dotted), ''
		(dashed), 'o' (circles), 'x ' (crosses), 'y '
		(yellow line), 'r' (red line), 'g' (green line)
<pre>plot ([xbegin xend],[ybegin yend])</pre>	:	draws a line from (xbegin, ybegin) to (xend, yend).
zoom	:	makes it possible to zoom in at a specific
		point in the graph by clicking at that point.
<b>ginput</b> (n)	:	gets the coordinates of n points in the graph,
		which are located by positioning the cursor
		and thereupon clicking the mouse.

<u>Remark:</u> help plot shows all the possible arguments with plot.

> x = [0:20]/10; y = sin (pi * x);		
$\gg$ <b>plot</b> (x,y);	%	plot sin πx on [0,2], <b>plot</b>
	%	automatically assigns the right
	%	dimensions to the graphical screen.
» axis ( [0 2 -1 1] );	%	adjust the x-axis and the y-axis; it is
	%	preferable to call axes after plot
» xlabel ('x'); ylabel ('sin x');		
» print	%	send the graph to the printer.
» clf		
» hold on		
$\gg type = ['-i'; i':i'; i-i']$	%	spaces to equalize the length of the
	%	character strings
» xgraph = [0:100]/100;		6
$\gg$ <b>for</b> $j = 1 : 4$		
omega = j * pi;		
ygraph = <b>sin</b> (omega * xgraph);	%	plot sin( $\omega x$ ) on [0,1] for $\omega = \pi$ , $2\pi$ ,
<b>plot</b> (xgraph,ygraph,type(j,:));	%	$3\pi$ , $4\pi$ distinguish the curves visually
end		
» <b>print</b> figure	%	store the graph in a file; use
-	%	help print to see a list of available
	%	formats.

The commands in favour of 3 dimensional graphs are:

:	plots a line through the coordinates of vectors x, y, z.
:	plots the matrix Z versus the vectors y and x, creating a
	surface.
:	same as surf, but adds a contour plot beneath the surface.
:	plots the matrix Z versus the vectors y and x, creating a mesh.
:	enables the user to rotate the plot by mouse.
	:

» $t = [0:500] * pi / 50;$		
$\gg x = sin(t); y = cos(t);$		
$\gg$ <b>plot3</b> (x,y,t)	%	plots a spiral on the cylinder
	%	$x^2 + y^2 = 1.$
$\gg x = [0:10] / 10;$		
$\gg y = [0:20] / 10;$		
» <b>for</b> j = 1:21	%	z = sin (x + y), note that
z(j, :) = sin(x + y(j));	%	x runs over columns and
end	%	y over rows.
> mesh(x,y,z);	%	<i>plot</i> $sin(x+y)$ <i>for</i> $x = 0 : 0.1 : 1$
	%	and $y = 0 : 0.1 : 2$

#### 14 Script files, function files

A script file is a file that consists of a sequence of Matlab commands: a Matlab program. We make such a file with the help of the Editor. The standard extension for these files is .m, e.g. program.m. Every Matlab command is closed off with <return>. This also holds for the last line of the sript file. The commands in the script file are executed after the filename is typed on the command line (without extension .m, i.e. in the example above you need to type 'program'). It is also possible to run a script file from Matlab programs (see chapter 17).

By means of function files we can add new functions to Matlab. A function file contains a sequence of commands, like a script file, but by means of input and ouput variables it is possible to communicate with other files. The filename of a function file, consisting of at the most 8 digits with standard extension .m, is used to execute the function.

Globally a function file has the following form:

The word function in the first line indicates it is not a script file.

<u>Remark</u>: At function\_name you need to fill in the file name without the extension .m .

Both the input variable as well as the output variable may be vectors.

*function y* = *average*(*v*); % This function computes the average of the elements of vector *v*.

n = length(v);y = sum(v)/n;

For the use of function files we refer to the example program (see section 17).

Variables used in a function file are local (i.e. only accessible inside the function), and therefore they are not stored in the Matlab memory.

function $y = comp(x);$ y = a * x;	% %	the variable a is defined locally and does not have a value
function $y = comp(x);$ a = 2;	% %	the variable a has the value 2, but only within this function
y = a * x;		

Often it is neccessary to use a variable in a function that gets its value outside the function. You can show Matlab you want to use such a variable by adding it to the list of parameters of that

function. In the following example we add the variable a to the list of parameters of the function comp:

function 
$$y = comp(x,a)$$
;  
 $y = a * x$ ; % the variable a gets its value outside the function and is  
% given to the function

This is not always possible. It may sometimes be necessary to define a variable globally, by using **global**. If you do so the variable is defined in all program parts that use the same declaration.

<i>function</i> $y = comp(x)$ ;		
global a;		
y = a * x;	%	the variable a is also defined globally at another
	%	location where a gets its value

<u>Remark</u>: The declaration with **global** should only be used when there is no other possibility. If you use it, it is wise to add some comments.

An example of a situation in which the occurrence of **global** is unavoidable is the usage of a library routine with a predefined function, where it is needed to supply the function with an additional parameter for a specific application.

quad(f,0,1);	%	library routine to compute the integral of the function
	%	f on [0,1]; the argument f refers to a user-supplied
	%	function file

function y = f(x); global m;  $y = x \wedge m$ ;

#### 15 Solving a system of equations

To solve systems of equations Ax = b we can use several methods:

i) If a small system with a full matrix needs to be solved only once without the need to go into details, we may use the black box option:

$$\gg x = A \setminus b;$$

Often it is necessary to go into more details to obtain an efficient program. As an example we mention:

ii) If more than one system needs to be solved, and A is the same but the right-hand side is always different:

$\gg [L, U] = lu(A);$	%	Make an LU-decomposition of A
$\gg y = L \setminus b;$	%	Solve lower triangular system
$\gg x = U   y;$	%	Solve upper triangular system
$\gg y2 = L \setminus b2; x2 = U \setminus y2;$	%	Solution for other right-hand side

iii) If the matrix is symmetric and positive definite, we may use the Cholesky decomposition:

$\gg R = chol(A);$	%	Make a Cholesky decomposition of $A$ : $R'R = A$
$\gg y = R' b;$	%	Solve lower triangular system
$\gg x = R   y;$	%	Solve upper triangular system

In all cases the command A = sparse(A) can save a lot of runtime and memory space when A is a band matrix. As an example we give the number of floating-point operations for the case where A is a symmetric tridiagonal matrix of size 100 x 100.

	without sparse(A)	with sparse(A)
method i	378350	2149
method ii	35250	1889
method iii	358750	1393

# 16 Tracking down errors

Matlab does not give specific directions for debugging programs. In any way it is useful to generate (intermediate) output, and if necessary to re-calculate it manually. Some useful commands are:

echo on	:	gives an echo-print of all Matlab commands that are executed. With this it is possible to locate the exact moment on which the program fails.
whos	:	gives a table of the variables that are stored in memory. With this command you can check the size.
size(A)	:	gives the size of a matrix A.
disp('labelj')	:	directs the labeled text to the screen; can be used to find out at which line the program does not work properly.
disp(var)	:	prints the actual value of the variable var on the screen. Can be used to check values of intermediate results.

# 17 Example program, time integration

% Filename % Function-file % Script-files	: exprog.m : exf.m : exheun.m, extabel.m	ex stands for example
% Screen manage	ment:	
clear;	% Clear work memory	
clc;	% Clear text window	
clf;	% Clear graphical screen	
y0=[1; 0];	% Int	itial condition
t0=0;	% Std	art time
tend=5;	% En	nd time
nrsteps=input('Gi	ive the number of steps:');	
h=(tend-t0)/nrstep	os; % Ti	me step
exheun	% Call for the script file contain	ing Heun's method
extabel	% Call for the script file designed to print the results	
	% The commands from a script	file are substituted directly into this program.
pause(5); hold on;	% The program pauses for a wh	ile before it shows the graph
,	h(1,:),'-',tgraph,ygraph(2,:),'');	% components of y are distinguished by % plotting the 2nd component with a broken line
axis([t0 tend -5 5]	7);	% it is preferable to call <b>axis</b> after <b>plot</b>
	problem: Name compulsory!');	
	with Heun with $h='$ num2str(h)]);	
hold off;		

% Heun's method. Script file	with filename exheun.m.
% Assuming (t0, y0) "nrsteps % The derivative of the diff. e % The results are put in tgrap	q. is given in the function file exf.m.
tgraph=[t0]; ygraph=[y0];	% start saving results
y=y0; t=t0; <b>for</b> j=1:nrsteps	
k1=h*exf(t,y); k2=h*exf(t+h,y+k1); ynew =y+(k1+k2)/2; tnew =t+h;	
tgraph=[tgraph tnew]; ygraph=[ygraph ynew];	% Paste the new results % after the old results
t=tnew; y=ynew;	
end;	

% Vectorfunction f. Function file with filename exf.m

function yacc = exf(t,y);

yacc = [-2\*y(1)-y(2)+t; -y(1)-2\*y(2)-t];

% Print result. Script file with file name extabel.m.

% The results which are stored in tgraph and ygraph are % printed in an 8-digit floating-point format in a table.

% In order to make a hardcopy of the tables you need to remove % the first and the last two comment symbols (%).

% fprintf is actually a C-command % In the format string of fprintf (the part between quotation marks), % text which needs to be printed is given, and for every number % which has to be printed the format is given.

%%5.1fmeans: fixed-point format with 1 decimal and 5 positions.%%15.7emeans: exponential format and floating-point with 7 decimals and 15 positions.%\nmeans: continue printing on the next line

% After the format string the variables which (possibly) need to be printed follow.

% the actual file starts now: % **diary** output

% diary off

% print every 10th result % note that nrsteps needs to a % multiple of 10.

% Results of the example program

Heun's method, h=0.100 step y(1) y(2)t 0.0 1.0000000e+00 0.000000e+00 0 5.2536330e-01 -2.9586400e-01 5 0.5 10 1.0 5.7914644e-01 -5.2647651e-01 15 1.5 8.4164231e-01 -8.2955459e-01 20 2.0 1.2051207e+00 -1.2023466e+00 25 2.5 1.6240001e+00 -1.6233635e+00 30 3.0 2.0751573e+00 -2.0750112e+00 35 3.5 2.5455986e+00 -2.5455650e+00 40 4.0 3.0276755e+00 -3.0276678e+00 3.5167996e+00 -3.5167979e+00 45 4.5 50 4.0101983e+00 -4.0101979e+00 5.0

% !lpr output % Make a hard copy of the file output

# 18 Example program, filling a penta-diagonal matrix

$\begin{cases} y \ w \ will give two methods in this example in order to construct the N x N dimensional pentadiagonal matrix A:  \begin{cases} y \ (x + b \ b \ a \ b \ b \ b \ a \ b \ b \ b \$		
$\begin{cases} 5 & \{ 5 - 4b \ 1 \ 0 \ 0 \ 0 \\ [-4+b \ 6 - 4-b \ 1 \ 0 \ 0 \\ [-4+b \ 6 - 4-b \ 1 \ 0 \\ [-6] 0 \ 1 - 4+b \ 6 - 4-b \ 1 \\ [-6] 0 \ 1 - 4+b \ 6 - 4-b \ 1 \\ [-6] 0 \ 1 - 4+b \ 6 - 4-b \ 1 \\ [-6] 0 \ 0 \ 1 - 4+b \ 6 - 4-b \ 1 \\ [-6] 0 \ 0 \ 1 - 4+b \ 6 - 4-b \ 1 \\ [-6] 0 \ 0 \ 0 \ 1 - 4+b \ 6 - 4-b \ 1 \\ [-6] 0 \ 0 \ 0 \ 1 - 4+b \ 6 - 4-b \ 1 \\ [-6] 0 \ 0 \ 0 \ 0 \ 1 - 4+b \ 6 - 4-b \ 1 \\ [-6] 0 \ 0 \ 0 \ 0 \ 1 - 4+b \ 6 - 4-b \ 1 \\ [-6] 0 \ 0 \ 0 \ 0 \ 0 \ 1 - 4+b \ 5 \\ [-6] 0 \ 0 \ 0 \ 0 \ 0 \ 1 - 4+b \ 5 \\ [-6] 0 \ 0 \ 0 \ 0 \ 0 \ 1 - 4+b \ 5 \\ [-6] 0 \ 0 \ 0 \ 0 \ 0 \ 1 - 4+b \ 5 \\ [-6] 0 \ 0 \ 0 \ 0 \ 0 \ 1 - 4+b \ 5 \\ [-6] 0 \ 0 \ 0 \ 0 \ 0 \ 1 - 4+b \ 5 \\ [-6] 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 1 - 4+b \ 5 \\ [-6] 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 $		nethods in this example in order to construct the $N \times N$ dimensional pentadiagonal matrix A:
$\begin{cases} i + i + b + b + i + 0 = 0 & i \\ 1 + i + b + b + i = 0 & i \\ 0 + i + i + b + i = 0 & i \\ 0 + i + i + b + i = 0 & i \\ 0 + i + i + b + i = 0 & i \\ 0 + i + i + b + i = 0 & i \\ 0 + i + i + b + i = 0 & i \\ 0 + i + i + b + b + i = 0 & i \\ 0 + i + i + b + b + i = 0 & i \\ 0 + i + i + b + b + i = 0 & i \\ 0 + i + i + b + b + i = 0 & i \\ 0 + i + i + b + b + i = 0 & i \\ 0 + i + i + b + b + i + i \\ 0 + i + i + b + b + i \\ 0 + i + i + b + b + i \\ 0 + i + i + b + b + i \\ 0 + i + b + b + i + i \\ 0 + i + i + b + b + i + i \\ 0 + i + i + b + b + i + i \\ 0 + i + i + b + b + i + i \\ 0 + i + i + b + b + i + i \\ 0 + i + i + b + b + i + i \\ 0 + i + i + b + b + i + i \\ 0 + i + i + b + b + i + i \\ 0 + i + i + b + b + i + i \\ 0 + i + i + b + b + i + i \\ 0 + i + i + b + b + i + i \\ 0 + i + i + b + b + i + i \\ 0 + i + i + b + b + i \\ 0 + i + i + b + b + i \\ 0 + i + i + b + b + i \\ 0 + i + i + b + i + i \\ 0 + i + i + b + i + i \\ 0 + i + i + b + i + i \\ 0 + i + i + b + i + i \\ 0 + i + i + b + i + i \\ 0 + i + i + b + i + i \\ 0 + i + i + i + b + i \\ 0 + i + i + i + i + i + i \\ 0 + i + i + i + i + i + i \\ 0 + i + i + i + i + i + i \\ 0 + i + i + i + i + i + i \\ 0 + i + i + i + i + i + i \\ 0 + i + i + i + i + i + i + i \\ 0 + i + i + i + i + i + i + i \\ 0 + i + i + i + i + i + i + i + i \\ 0 + i + i + i + i + i + i + i + i \\ 0 + i + i + i + i + i + i + i + i + i +$		5 - 4 - b = 1 - 0 - 0 - 0 = 1
$\begin{cases} & \left[ \begin{array}{c} 1 - 4+b & 6 - 4-b & 1 & 0 \\ 0 & 1 - 4+b & 6 - 4-b & 1 \\ 0 & 0 & 1 - 4+b & 6 - 4-b & 1 \\ 0 & 0 & 1 - 4+b & 6 - 4-b & 1 \\ 0 & 0 & 1 & -4+b & 6 - 4-b \\ 1 & 0 & 0 & 0 & 1 - 4+b & 6 - 4+b \\ 1 & 0 & 0 & 0 & 1 - 4+b & 6 - 4+b \\ 1 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 - 4+b & 5 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 &$	L.	
$\begin{cases} A = c \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 4+b & 6 & 4+b & 1 & 0 \\ 0 & 0 & 1 & 1 & 4+b & 6 & 4+b & 1 \\ 0 & 0 & 0 & 1 & 1 & 4+b & 6 & 4+b & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 &$	L.	1
$\begin{cases} S = A = c \begin{bmatrix} 0 & 1 & -4 + b & 6 & -4 - b & 1 & 0 \\ 0 & 0 & 1 & -4 + b & 6 & -4 - b \\ 1 & 0 & 0 & 0 & 1 & -4 + b & 5 & 1 \\ 1 & 0 & 0 & 0 & 0 & 1 & -4 + b & 5 & 1 \\ 1 & 0 & 0 & 0 & 0 & 1 & -4 + b & 5 & 1 \\ 1 & 0 & 0 & 0 & 0 & 1 & -4 + b & 5 & 1 \\ 1 & 0 & 0 & 0 & 0 & 1 & -4 + b & 5 & 1 \\ 1 & 0 & 0 & 0 & 0 & 1 & -4 + b & 5 & 1 \\ 1 & 0 & 0 & 0 & 0 & 1 & -4 + b & 5 & 1 \\ 1 & 0 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 0 & 1 & -4 + b & 5 & -4 + b \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 &$	%	0 1 -4+b 6 -4-b 1
$\begin{cases} 0 & 1 & -4+b & 6-4-b & 1 & 0 \\ 0 & 0 & 1 & -4+b & 6-4-b & 1 \\ 0 & 0 & 0 & 0 & 1 & -4+b & 6-4+b \\ 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -4+b & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 &$	L	]
$\begin{cases} 0 & 0 & 1 & -4+b & 6-4+b & 1 \\ 0 & 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 1 & -4+b & 5 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 &$	L	
$\begin{cases} 6 & 1 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 1 \\ -4+b \\ 5 \\ \end{cases}$ $\begin{cases} 6 & 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \\ -4+b \\ 5 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1$	· · ·	
% where c and b are given constants. Note that the matrix A is symmetric for b = 0. % Method 1: Construction using a loop. % In order to make the commands in the loop also valid for the first and the last column we first add some extra columns. B=zeros(N,N+4); % Creates a N x (N+4) matrix, consisting of zeros for j=1:N     B(j,jj+4)=c*{(1-4+b 6-4-b 1];     end; % lassigns values to the coefficients B(j,j), B(j,j+1), B(j,j+2), B(j,j+3) and B(j,j+4) A=B(:,3:N+2); % Copies B, without the first two and last two columns clear B; % Removes temporary matrix B  A(1,1)=5*c; A(N,N)=5*c; % Changes the upper-left and the lower-right coefficient of A  A=sparse(A); % Only the non-zero elements of A are stored into the memory. % When N is large it is better to use the non-zero elements of A only. % For an LU-decomposition this saves computing time as well as memory % space. % Method 2: Construction on the basis of the diagonals of A % Firstly we make 5 vectors, all containing the elements of a diagonal.  wm2 = c * ones(N-2.1); % This diagonal contains (N-2) elements, all equal to c  vp2 = c * ones(N-2.1); % The first and last element of the main diagonal have different values. % We construct a column vector consisting of sixes, by 6 * ones(N-2.1), % We construct a column vector consisting of sixes, by 6 * ones(N-2.1), % We construct a column vector consisting of sixes, by 6 * ones(N-2.1), % We construct a column vector consisting of sixes, by 6 * ones(N-2.1), % We construct a column vector consisting of sixes, by 6 * ones(N-2.1), % Hor is main diagonal bace and the diagonal have different values. % the semicolons because we are making a column vector.	L.	
<pre>% where c and b are given constants. Note that the matrix A is symmetric for b = 0. % Method 1: Construction using a loop. % In order to make the commands in the loop also valid for the first and the last column we first add some extra columns. B=zeros(N,N+4); % Creates a N x (N+4) matrix, consisting of zeros for j=1:N</pre>	%	0  0  0  0  1  -4+b  5
% Method 1: Construction using a loop. % In order to make the commands in the loop also valid for the first and the last column we first add some extra columns. B=zeros(N,N+4); % Creates a N x (N+4) matrix, consisting of zeros for j=1:N $B(j,j;+4)=c^*[1-4+b \ 6-4-b \ 1]$ ; end; % Assigns values to the coefficients $B(j,j)$ , $B(j,j+1)$ , $B(j,j+2)$ , $B(j,j+3)$ and $B(j,j+4)$ A=B(:,3:N+2); % Copies B, without the first two and last two columns clear B; % Removes temporary matrix B $A(1,1)=5^*c;$ $A(N,N)=5^*c;$ % Changes the upper-left and the lower-right coefficient of A A=sparse(A); % Only the non-zero elements of A are stored into the memory. % When N is large it is better to use the non-zero elements of A only. % For an LU-decomposition this saves computing time as well as memory % space. % Method 2: Construction on the basis of the diagonals of A % Firstly we make 5 vectors, all containing the elements of a diagonal. $vm2 = c^* ones(N-2,1);$ % This diagonal contains (N-2) elements, all equal to c $vp2 = c^* ones(N-2,1);$ with first and last element of the main diagonal have different values. $y = c^* (5: 6^*ones(N-2,1);$ % The first and last element of the main diagonal have different values. % We construct a column vector consisting of sizes, by 6* ones(N-2,1), $y = c^* (5: 6^*ones(N-2,1); + 0$ The first and last element of the main diagonal have different values. $y = b^* (5: 6^*ones(N-2,1); + 0$ The first and last element of the main diagonal have different values. $y = b^* (5: 6^*ones(N-2,1); + 0$ The first and last element of the main diagonal have different values. $y = b^* (5: 6^*ones(N-2,1); + 0$ The first and last element of the main diagonal have different values. $y = b^* (5: 6^*ones(N-2,1); + 0$ The first and last element of the main diagonal have different values. $y = b^* (5: 6^*ones(N-2,1); + 0$ The first and last element of the main diagonal have different values. $y = b^* (5: 6^*ones(N-2,1); + 0$ The first and last element of the main diagonal have different val		given constants. Note that the matrix 4 is symmetric for $\mathbf{b} = 0$
% In order to make the commands in the loop also valid for the first and the last column we first add some extra columns. B=zeros(N,N+4); % Creates a N x (N+4) matrix, consisting of zeros for j=1:N B(j,j;j+4)=c*[1-4+b 6-4-b 1]; end; % Assigns values to the coefficients B(j,j), B(j,j+1), B(j,j+2), B(j,j+3) and B(j,j+4) A=B(:,3:N+2); % Copies B, without the first two and last two columns clear B; % Removes temporary matrix B A(1,1)=5*c; A(N,N)=5*c; % Changes the upper-left and the lower-right coefficient of A A=sparse(A); % Only the non-zero elements of A are stored into the memory. % When N is large it is better to use the non-zero elements of A only. % For an LU-decomposition this saves computing time as well as memory % space. % Method 2: Construction on the basis of the diagonals of A % Firstly we make 5 vectors, all containing the elements of a diagonal. vm2 = c* ones(N-2,1); % This diagonal contains (N-2) elements, all equal to c vp2 = c* ones(N-2,1); 5; % The first and last element of the main diagonal have different values. % We construct a column vector consisting of sizes, by 6* ones(N-2,1), % and add the fives at the beginning and the end. Note that we use % the semicolons because we are making a column vector. A=diag(vm2,-2)+diag(vm1,-1)+diag(v,0)+diag(vp1,1)+diag(vp2,2); clear vm2 vm1 v vp1 vp2	70 where c and b are	given constants. Note that the matrix $A$ is symmetric for $b = 0$ .
for j=1:N $B(j,j;j+4)=c^*[1-4+b-6-4-b-1];$ end; % Assigns values to the coefficients $B(j,j)$ , $B(j,j+1)$ , $B(j,j+2)$ , $B(j,j+3)$ and $B(j,j+4)$ A=B(:,3:N+2); % Copies B, without the first two and last two columns clear B; % Removes temporary matrix B $A(1,1)=5^*c;$ % Changes the upper-left and the lower-right coefficient of A A=sparse(A); % Only the non-zero elements of A are stored into the memory. % When N is large it is better to use the non-zero elements of A only. % For an LU-decomposition this saves computing time as well as memory % Space. % Method 2: Construction on the basis of the diagonals of A % Firstly we make 5 vectors, all containing the elements of a diagonal. $vm2 = c^*$ ones(N-2,1); % This diagonal contains (N-2) elements, all equal to c $vp2 = c^*(b-4)*ones(N-1,1);$ $vp1 = c^*(b-4)*ones(N-1,1);$ $vp1 = c^*(b-4)*ones(N-1,1);$ $v = c^*[5: 6*ones(N-2,1); 5];$ % The first and last element of the main diagonal have different values. % We construct a column vector consisting of sizes, by 6 * ones(N-2,1), % and add the fives at the beginning and the end. Note that we use % the semicolons because we are making a column vector. A=diag(vm2,-2)+diag(vm1,-1)+diag(vp1,1)+diag(vp2,2); clear vm2 vm1 v vp1 vp2		
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<pre>vm1 = c*(b-4)*ones(N-1,1); vp1 = c*(-b-4)*ones(N-1,1); v =c*[5; 6*ones(N-2,1); 5]; % The first and last element of the main diagonal have different values. % We construct a column vector consisting of sixes, by 6 * ones(N-2,1), % and add the fives at the beginning and the end. Note that we use % the semicolons because we are making a column vector. A=diag(vm2,-2)+diag(vm1,-1)+diag(v,0)+diag(vp1,1)+diag(vp2,2); clear vm2 vm1 v vp1 vp2</pre>		0 1 1
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clear vm2 vm1 v vp1 vp2		% the semicolons because we are making a column vector.
clear vm2 vm1 v vp1 vp2	A=diag(vm2,-2)+di	ag(vm1,-1)+diag(v,0)+diag(vp1,1)+diag(vp2,2);
A= <b>sparse</b> (A); % See above		
	A=sparse(A):	% See above
	~ <b>r</b>	

## **19 Reference and index**

In this section the following notation holds:

- n,m scalar
- A matrix
- v,w,b vector
- x,y arbitrary
- *f* user supplied function file

Comand	Explanation	Page
[]	are used for creating matrices and vectors	
()	are used to :	
	- indicate the order of operations	
	- embrace arguments of functions	
	- embrace indices of matrices and vectors	
•••	Three or more dots at the end of a line indicate that the line continues	6
	on the next line	
,	symbol that separates between row elements in a matrix.	4
;	symbol that separates between distinct rows in a matrix. We can also	6
	use the semicolon to suppress the display of computations on the	
	screen and to separate different commands on one line	
%	All text on a line after the symbol % will be regarded as comment	4
!	used to insert operating system commands	4
:	used for the generation of variables in for-loops and used to select	
	matrix elements: $A(:,n)$ is the n <sup>th</sup> column of A, $A(m,:)$ the m <sup>th</sup> row	
,	transposes matrices and vectors	13
*	v.* w : multiplication of two vectors by multiplying element by	
	element	
\	A\b gives the solution of $Ax = b$	
^	$x \wedge y = x$ to the power y	
&	logical and	16
	logical or	16
2	logical not	16
abs	<b>abs</b> (x) is the absolute value of (the elements of) x	10,15
atan	<b>atan</b> (x) is the arctangent of (the elements of) x	15
axis	<b>axis</b> (v), with $v = [xmin xmax ymin ymax]$ replaces the automatical	21
	scaling of a graph's axes by the configuration given by the vector v.	
	axis ('square') switches over from a rectangular graphical screen to a	
	square-shaped graphical screen, axis ('normal') switches back to the	
	rectangular screen.	
chol	<b>chol</b> (A) yields the Cholesky decomposition of the matrix A.	15
clc	clc clears the command window and moves the cursor to the upper left	7
	corner	

clear	<b>clear</b> clears the variables from the Matlab memory. <b>clear</b> $x \{y\}$	7
	removes the variable x {and y}	
clf	clf clears the graphical window	7,21
cos	<b>cos</b> (x) is the cosine of (the elements of) x	15
cputime	cputime determines the cpu time	7
demo	demo starts a demonstration	4,7
diag	<b>diag</b> $(v,k)$ returns a square matrix with the elements of the vector v on the k <sup>th</sup> upper diagonal	12
diary	<b>diary</b> <i>filename</i> puts all following commands and results in a file with the name <i>filename</i> . This stops after <b>diary off</b> is entered	19
disp	<b>disp</b> (' <i>text</i> ') writes <i>text</i> on the screen. <b>disp</b> (x) displays the value of the variable x, without variable name	8,19, 26
echo	<b>echo on</b> lets Matlab display every executed command when a script file runs. <b>echo off</b> switches it off	26
eig	eig(A) computes the eigenvalues of A and returns a vector containing these eigenvalues	15
else, elseif	see if	
end	end is the command that closes off loop statements and conditional statements	
exp	exp(x) is the exponent of (the elements of) x with base e	15
eye	<b>eye</b> (n) is the nxn identity matrix. <b>eye</b> (m,n) is an mxn matrix with ones on the diagonal and zeros elsewhere	11
for	loop statement: <b>for</b> variable = start value : increment : end value, commands <b>end</b>	5,18
format	formats the output:         format short       - 5 digits, fixed point         format short e       - 5 digits, floating point         format long       - 15 digits, fixed point         format long e       - 15 digits, floating point         standard configuration is short.       - 15 digits extra empty lines in the output         format loose adds empty lines	8
fprintf	C-command for advanced formatting of output	19
function	user defined function: <b>function</b> outputvar = <i>functionname</i> (inputvars) commands <b>end</b>	23
	Function files have to have the name <i>functionname.m.</i> The name <i>functionname</i> may contain up to 8 letters.	
ginput(n)	gets the coordinates of n points in the graph, which are located by positioning the cursor and thereupon clicking the mouse	21
global	global x changes x into a global variable	24
grid	adds a grid (a lattice of horizontal and vertical lines) to a graph	21

help	help shows the functions you can get information about.	4,7
погр	Help functionname shows this information on the screen. Helpwin	
	generates an extra window with helptopics	
hold	<b>hold on</b> keeps the last plot in the graphical screen. Therefore a graph	21
	will be plotted on top of the existing one. <b>Hold off</b> restores the default	
	settings. In this case, when a plot command has been given, the	
	graphical screen will be cleared before the new graph will be plotted	
i	the imaginairy unit	15
if	conditional statement:	16
	if statement if statement	
	commands commands	
	else elseif statement	
	commands commands	
	end else	
	commands	
	end	
imag	imag(c) returns the imaginary part of the complex number c	10
input	<b>input</b> (' <i>text</i> ') displays <i>text</i> on the screen and waits for input by the user.	20
	Can be assigned to a variable	
length	<b>length</b> (v) returns the number of elements of the vector v	13
load	load <i>filename</i> loads the variables of the file <i>filename</i> into the memory.	20
	The file is of type .mat or of type .txt.	
log	log(x) is the natural logarithm of (the elements of) x	15
log10	log10(x) is the logarithm with base 10 of (the elements of) x	15
lu	lu(A) computes the lu decomposition of the matrix A	15
max	<b>max</b> (v) returns the largest element of the vector v	13,15
mesh	<b>mesh</b> (x,y,Z) plots the matrix Z versus the vectors y and x, creating a	22
	mesh	
min	<b>min</b> (v) returns the smallest element of the vector v	15
norm	<b>norm</b> (v) computes the Euclidian norm of v and <b>norm</b> (v, inf) computes	13
	the infinity norm	
num2str	<b>num2str</b> ( <i>var</i> ) converts the number <i>var</i> to a text string	21
ones	<b>ones</b> (n) is an nxn matrix filled with ones, <b>ones</b> (m,n) is an mxn matrix	11
pause	pause pauses the running programme and waits until the user presses	4,7
	any key. Pause(n) pauses during n seconds	
рі	<b>pi</b> is the machine's representation of $\pi$	15
plot	Drawing a graph:	4,12,
	<b>plot</b> (v) - plot the vector v versus its indices	21
	<b>plot</b> (v,w) - plot the vector w versus the vector v	
	<b>plot</b> (m,n,'symbol') - put a symbol at position (m,n) in the	
	graph. The following symbols can be	
	used: +, *, o and x	
plot3	<b>plot3</b> (x,y,z) plots a line through the coordinates of vectors x, y, z	22
print	direct the graph to the printer. <b>Print</b> <i>filename</i> stores the graph in the	21
	file <i>filename</i>	

quad	library routine: $quad(f, 0, I)$ computes the integral of the function f on	24
_	[0,1].	
quit	logout from Matlab	7
real	real (c) returns the real part of the complex vector c	10
rem	<b>rem</b> (m,n) returns the remainder after division of m by n	15
rotate3d	enables the user to rotate the plot by mouse	22
round	<b>round</b> (x) rounds the elements of x to the nearest integer	15
save	<b>save</b> <i>filename</i> x {y} saves the variable x {and y} into the file <i>filename</i> .mat	19
script file	a script file is a file consisting of a sequence of Matlab commands. After you have typed the file name at the command prompt these commands will be executed.	23f
shg	shg shows the most recent graphical screen	7,21
sin	sin(x) is the sine of (the elements of) x	5,15
size	[m,n] = size(A) returns the size of the matrix A	13,26
sparse	<b>sparse</b> (A) saves computations as well as memory space. It can be used when A is a band matrix, and the computations only involve non-zero elements (see section 15).	25
sqrt	<b>sqrt</b> (x) is the square root of (the elements of) x	13,15
sum	<b>sum</b> (v) is the sum of the elements of the vector of v	15
surf	<b>surf</b> (x,y,Z) plots the matrix Z versus the vectors y and x, creating a surface	22
surfc	same as <b>surf</b> , but adds a contour plot beneath the surface	22
tan	tan(x) is the tangent of (the elements of) x	15
text	<b>text</b> (m,n,' <i>text</i> ') writes <i>text</i> at position (m,n) of the graphical screen	21
title	<b>title</b> (' <i>text</i> ') writes <i>text</i> as a title above the graph in the graphical screen	21
while	conditional loop statement:	18
	while statement commands end	
whos	whos shows the name, size and type of the variables in the Matlab memory	7,9, 26
xlabel	<b>xlabel</b> (' <i>text</i> ') places <i>text</i> underneath the x-axis of the graphical screen	21
ylabel	ylabel('text') places text next to the y-axis of the graphical screen	21
zeros	<b>zeros</b> (n) returns an nxn matrix with zeros; <b>zeros</b> (m,n) returns an mxn matrix	11
zoom	<b>zoom</b> makes it possible to zoom in at a specific point in the graph by clicking the mouse at that point	21